

# **A STUDY ON THE IMPORTANCE OF C ALGEBRA IN LATTICE THEORY**

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## ***ABSTRACT***

*Lattice theory not only a necessary tool in the development of modern algebra in general and Universal algebra in particular. Lattice theory plays a major role in simplifying, unifying and generalizing many aspects of Mathematics and resembles Group theory, General topology and Functional analysis, because its central concept that of order, inter wines through almost all mathematics. The beauty of Lattice theory is in its extreme simplicity of the basic concept, which is order or partial order, one gets interesting generalization of lattice concept by dropping one or more of the lattice identities.*

*Keywords: Lattice, C Algebra, Bounded*

## **INTRODUCTION**

In 1854, George Boole (1815–1864) introduced an important class of algebraic structures in his research work on mathematical logic. In his honor these structures have been called Boolean algebras. These are special type of lattices. In particular, congruence lattices play an important role. It was E. Schroder, who about 1890, considered the lattice concept in today's sense.

At approximately the same time, R. Dedikind developed a similar concept in his work on groups and ideals. Dedikind defined modular and distributive lattices which are types of lattices of that are important in applications. The rapid development of lattice theory started around 1930. We could say that Boolean lattices or Boolean algebras are the simplest and at the same time the most important lattices for applications.

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## Lattice Theory

It was Garrett Birkhoff's work in the mid thirties that started the general development of lattice theory. In a Brilliant series of papers he demonstrated the importance of the lattice theory and showed that it ii provides a unifying framework for previously unrelated developments in any mathematical disciplines.

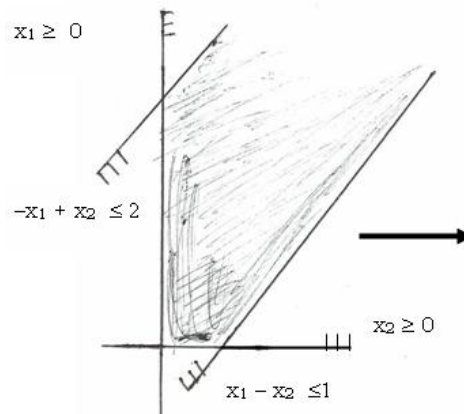
During a pivot step, we make the value of a nonbasic variable just large enough to get the value of a basic variable down to zero. This, however, might never happen.

If we now try to bring  $x_2$  into the basis by increasing its value, we notice that none of the tableau equations puts a limit on the increment. We can make  $x_2$  and  $z$  arbitrarily large the problem is unbounded.

By letting  $x_2$  go to infinity we get a feasible halfline - starting from the current BFS - as a witness for the unboundedness. In our case this is the set of feasible solutions

example

$$\begin{aligned}
 &\text{maximize} && x_1 \\
 &\text{subject to} && x_1 - x_2 \leq 1, \\
 &&& -x_1 + x_2 \leq 2, \\
 &&& x_1, x_2 \geq 0.
 \end{aligned}$$



with initial tablean

$$\begin{aligned}
 x_3 &= 1 - x_1 + x_2 \\
 x_4 &= 2 + x_1 - x_2 \\
 \hline
 z &= x_1
 \end{aligned}$$

After one pivot step with  $x_1$  entering the basis we get the tableau :

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$$x_1 = 1 + x_2 - x_3$$

$$x_4 = 3 - x_3$$

$$z = 1 + x_2 - x_3$$

$$\{(1,0,0,3) + x_2(1, 1, 0, 0) \mid x_2 \geq 0\}.$$

Such a halfline will typically be the output of the algorithm in the unbounded case. Thus, unboundedness can quite naturally be handled with the existing machinery. In the geometric interpretation it just means that the feasible polyhedron  $P$  is unbounded in the optimization direction.

While, we can make some nonbasic variable arbitrarily large in the unbounded case, just the other extreme happens in the degenerate case: some tableau equation limits the increment to zero so that no progress in  $z$  is possible.

The only candidate for entering the basis is  $x_2$ , but the first tableau equation shows that its value cannot be increased without making  $x_3$  negative. This may happen whenever in a BFS some basic variables assume zero value, and such a situation is called degenerate. Unfortunately, the impossibility of making progress in this case does not imply optimality, so we have to perform a 'zero progress' pivot step. In our example, bringing  $x_2$  into the basis results in another degenerate tableau with the same BFS.

$$\begin{array}{rcl} x_2 & = & x_1 - x_3 \\ x_4 & = & 2 - x_1 \\ \hline z & = & x_1 - x_3 \end{array}$$

Nevertheless, the situation has improved. The nonbasic variable  $x_1$  can be increased now, and by entering it into the basis, we already obtain the final tableau

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$$\begin{array}{rcl}
 x_1 & = & 2 \quad \quad \quad - x_4 \\
 x_2 & = & 2 \quad - x_3 \quad - x_4 \\
 \hline
 z & = & 2 \quad - x_3 \quad - x_4
 \end{array}$$

With optimal BFS  $x = (x_1 \dots\dots x_4) = (2,2,0,0)$

In this example, after one degenerate pivot we were able to make progress again. In general, there might be longer runs of degenerate pivots. Even worse, it may happen that a tableau repeats itself during a sequence of degenerate pivots, so the algorithm can go through an infinite sequence of tableaus without ever making progress. This phenomenon is known as cycling, and an example can be found. If the algorithm does not terminate, it must cycle. This follows from the fact that there are only finitely many different tableaus.

$$\begin{array}{rcl}
 x_B & = & \beta \quad - \quad \Lambda x_N \\
 \hline
 z & = & z_0 \quad + \quad \gamma^T x_N,
 \end{array}$$

and assume there is another tableau  $T_0$  with the same basic and nonbasic variables, i.e.  $T$  is the system

$$\begin{array}{rcl}
 x_B & = & \beta' \quad - \quad \Lambda' x_N \\
 \hline
 z & = & z_0' \quad + \quad \gamma'^T x_N,
 \end{array}$$

By the tableau properties, both systems have the same set of solutions. Therefore

$$\begin{array}{l}
 \beta - \beta' - \Lambda - \Lambda' x_{N'} = 0 \text{ and} \\
 z_0 - z_0' + \gamma^T - \gamma'^T x_N = 0
 \end{array}$$

must hold for all d-vectors  $x_N$ , and this implies

$$\beta = \beta', \Lambda = \Lambda', \gamma = \gamma' \text{ and } z_0 = z_0'$$

Hence

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$$T = T'$$

There are two standard ways to avoid cycling:

- Bland's smallest subscript rule: If there is more than one candidate  $x_k$  for entering the basis or more than one candidate for leaving the basis, which is another manifestation of degeneracy, choose the one with smallest subscript  $k$ .
- Avoid degeneracies altogether by symbolic perturbation. By Bland's rule, there is always a way of escaping from a sequence of degenerate pivots.

For this, however, one has to give up the freedom of choosing the entering variable. For us it will be crucial not to restrict the choice of the entering variable, so we will abandon Bland's rule and instead resort to the method of symbolic perturbation, although this requires more computational effort.

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